

## Problem Solving Strategies: Sampling and Heuristics

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#### Outline

Methodological Differences Inverses vs. Inferences

Problem Transformation From Inference to Searching

Rewarding Insights Why Source Separation is Difficult

Solution

**Heuristics and Sampling** 

#### The Curse of Uncertainty

A system can be in one state of a set of possible states

S1 •
S2 •
S3 •
S4 •
S5 •

A system can be in one state of a set of possible states We can make measurements of the system

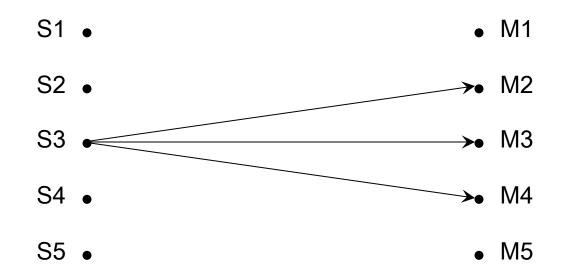


A system can be in one state of a set of possible states We can make measurements of the system



Ideally, each state maps to one and only one measurement

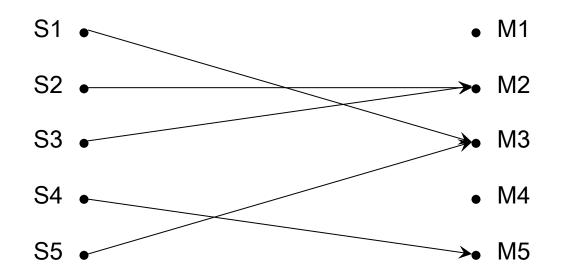
A system can be in one state of a set of possible states We can make measurements of the system



Ideally, each state maps to one and only one measurement However, noise can corrupt the measurement

### The Inverse is Most Likely Not Defined

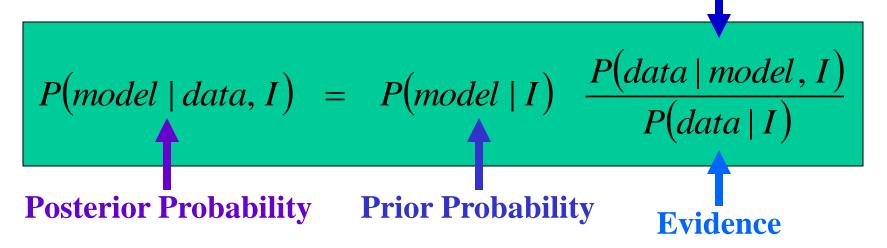
This uncertainty means that we are not assured of having a one-to-one mapping from the states to the measurements



Thus, the inverse mapping is not assured to exist!

#### **Source Separation as Inference**

Since there is not enough information to obtain a unique solution, we are left to infer the most probable solution. Likelihood

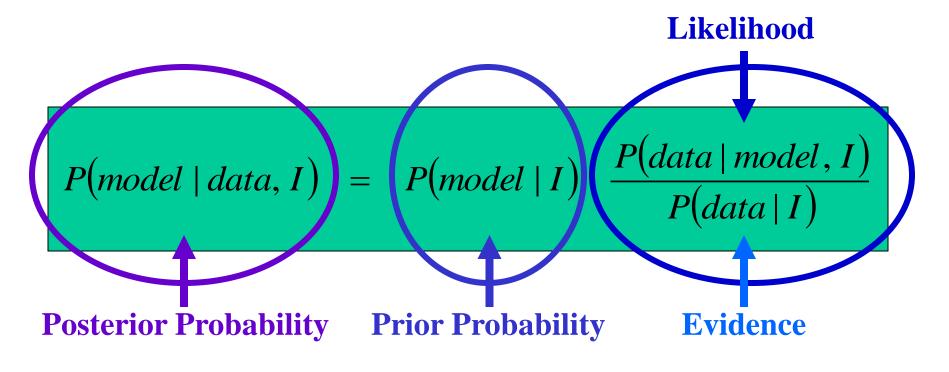


Bayes Theorem describes how our prior knowledge about a model, based on our prior information *I*, is modified by the acquisition of new information or data:

### **Machine Learning**

#### Bayes Theorem is a learning rule.

The Prior Probability describes what you first knew. Multiply this by a term that describes the effect of your new information, and the result is what you know after you have taken into account your new data.



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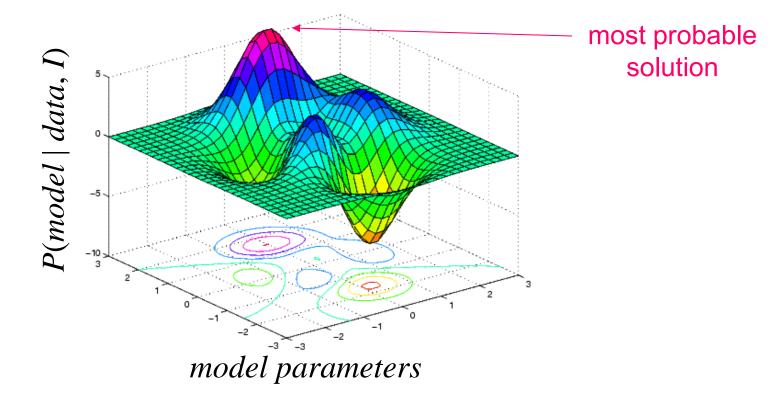
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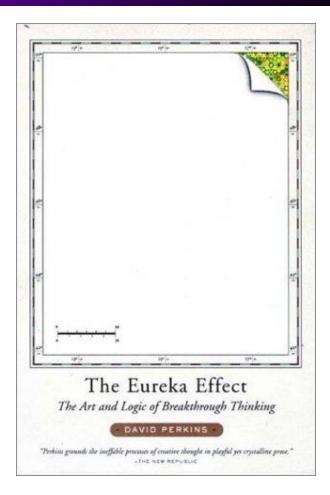
**Heuristics and Sampling** 

### From Inference to Searching

The Posterior Probability can be viewed as an optimization criterion that is to be maximized. This *recasts the inference problem into a search problem* where we search the space of model parameters to find the high probability regions



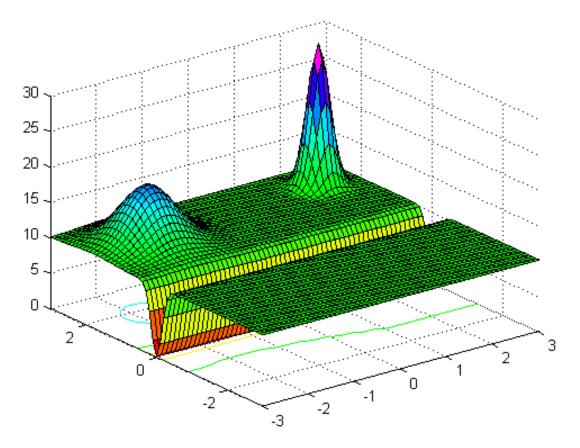
#### The Art and Logic of Breakthrough Thinking



#### **David Perkins (Harvard)**

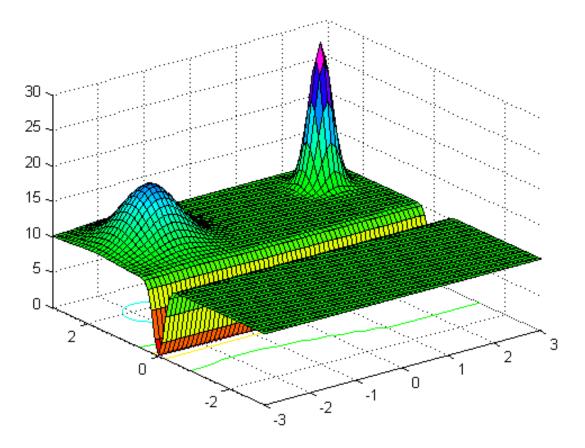
#### **Klondike Space**

David Perkins describes these spaces as Klondike spaces. There is gold in the hills, but the terrain is treacherous!



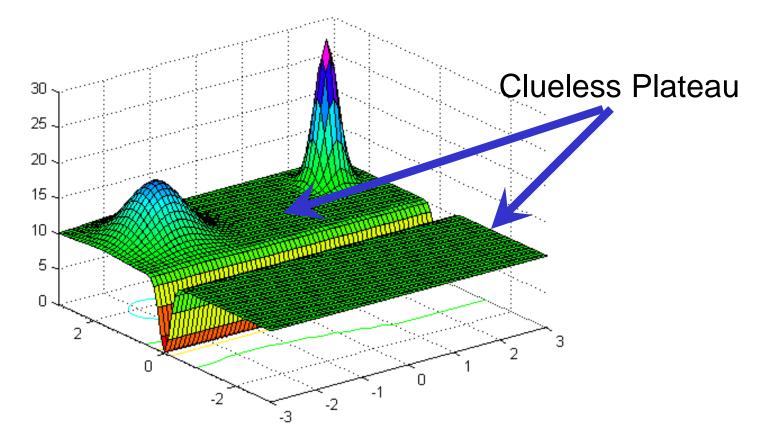
#### Wilderness Trap

The **Wilderness Trap** is characterized by the space having a large volume to search over. This is increasingly problematic in higher-dimensions.



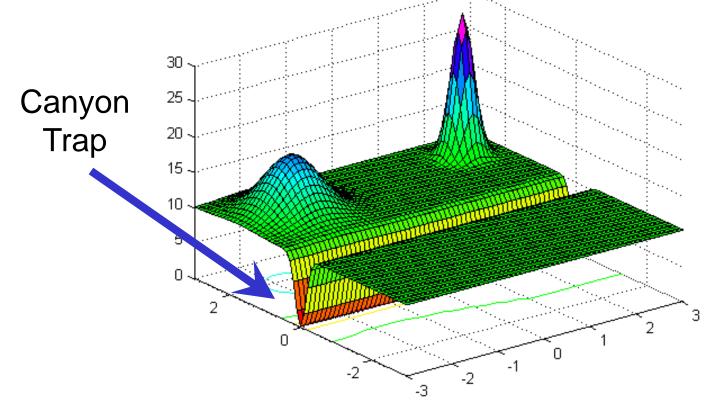
#### **Clueless** Plateau

The **Clueless Plateau** is characterized by a flat region of the space that provides no hints as to where the peak might be.



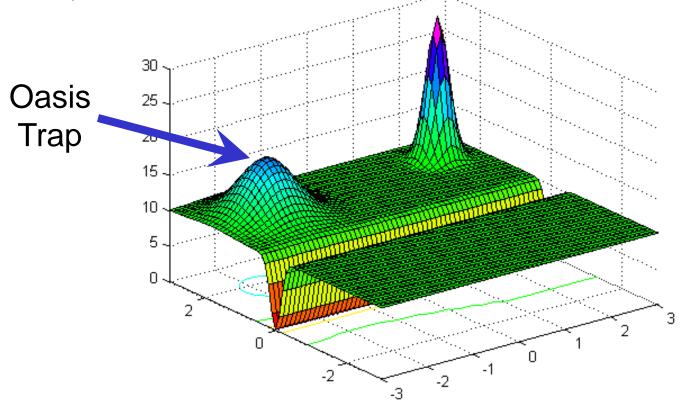
### Narrow Canyon of Exploration

The **Canyon Trap** is characterized by artificially constrained exploration within an extensive low probability region. This arises from not considering all the possible solutions to a problem.



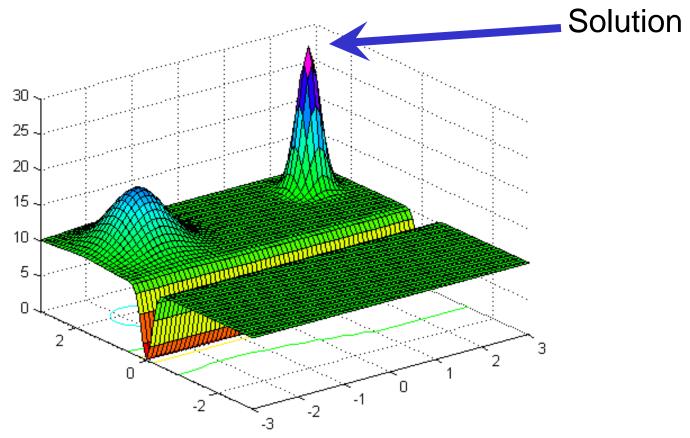
#### **Oasis of False Promise**

The **Oasis Trap** is characterized by a local maximum that is so tempting that it is almost impossible to move away from. However, it is not the solution.

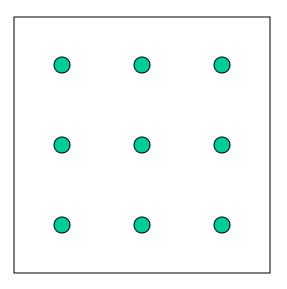


#### **True Solution**

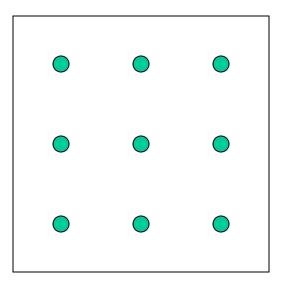
The **Solution** may occupy a relatively small volume in the space making it extremely difficult to find.



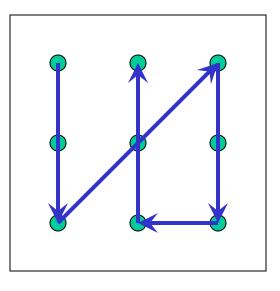
#### **Puzzles as Challenging Problems**



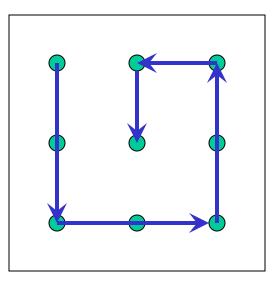
# Without lifting your pencil off the page, connect the dots using only 4 straight lines



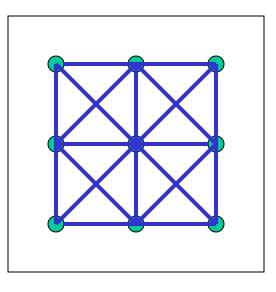
Wilderness Trap: Very many ways of drawing 4 straight lines



**Wilderness Trap**: Very many ways of drawing 4 straight lines **Oasis Trap**: Many close solutions using 5 lines



Wilderness Trap: Very many ways of drawing 4 straight lines Oasis Trap: Many close solutions using 5 lines Clueless Plateau: Close solutions do not provide insight

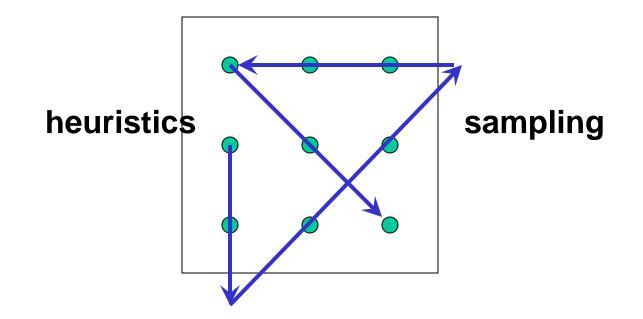


Wilderness Trap: Very many ways of drawing 4 straight lines Oasis Trap: Many close solutions using 5 lines Clueless Plateau: Close solutions do not provide insight Canyon Trap: Focused on subspace of possible solutions

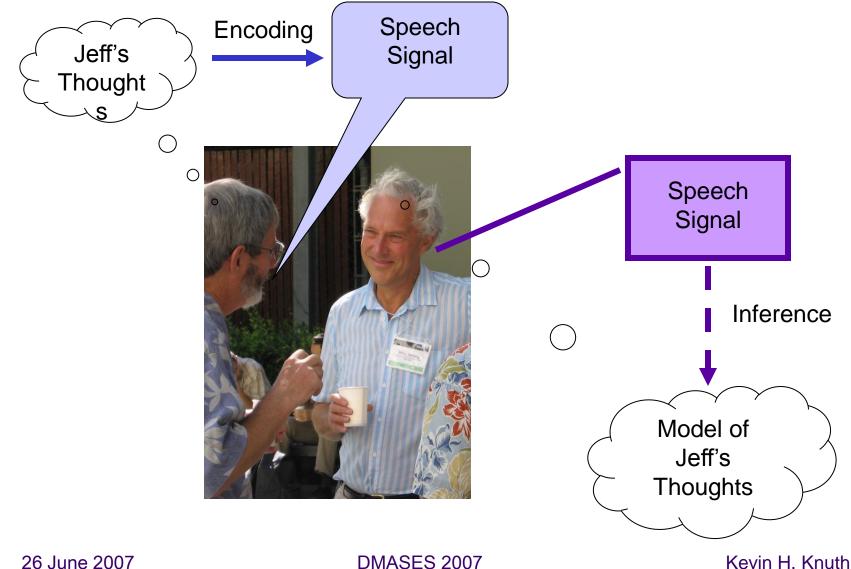
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#### **Search Strategies**

To overcome the topological difficulties of the search space, one must **balance educated guesses with exploration** 



#### **Communication as a Problem**



### Jokes Rely on Difficult Topography



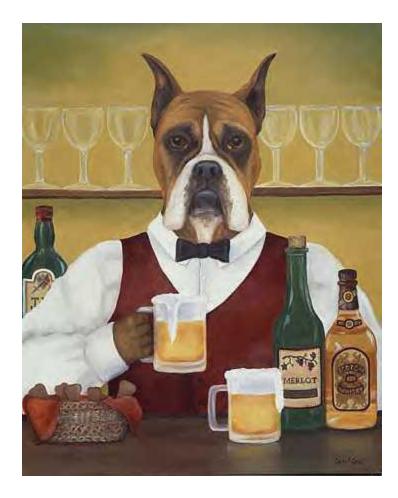
A String Walks into a Bar

He Sits Down and Orders a Beer



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#### The Bartender says, "We don't serve strings here!"

#### "Go on! Get outta here!!"



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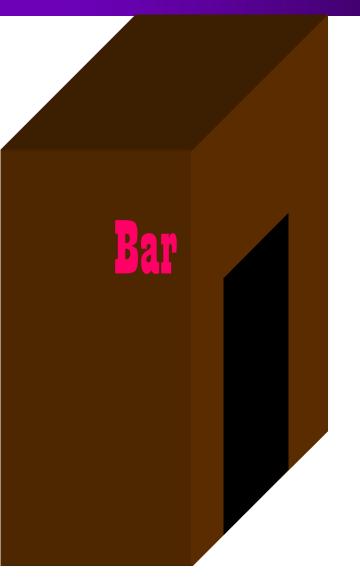
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The String leaves Frustrated.

When he gets outside, he messes up his hair and tangles himself until he is virtually unrecognizable.

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The String goes back into the Bar.

He sits down and orders a Beer.



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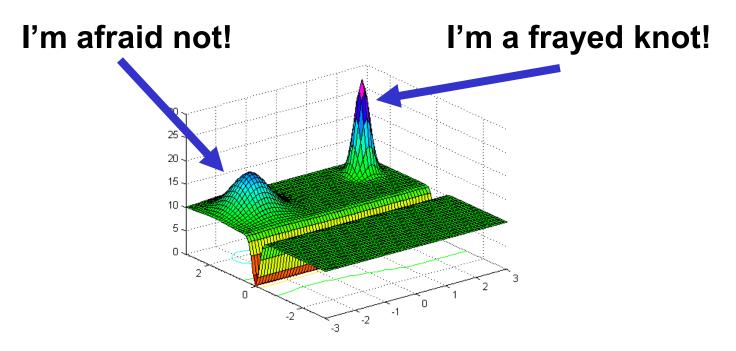


The Bartender looks at him funny and says, "Aren't you that stupid String who was just in here?"

The String replies "No ..."

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### Why Jokes are Funny



Several classes of jokes are funny because they pose problems that are difficult to solve. The problem is that of inferring the my meaning (model) from my speech (data).

This joke relies on an Oasis Trap!

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What is the difference between:

A person who drives and steers their way to work every day and

The set of operations {driving and steering}?



What is the difference between:

A person who drives and steers their way to work every day and

The set of operations {driving and steering}?



#### One commutes and the other doesn't!

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### **Problem of Limited Solution Space**

This joke is again funny because of the Oasis Trap.

However, this joke fails, because the solution lies in a part of the space not accessible by many members of the audience. There is a Canyon Trap imposed by the nature of the joke itself.

In Comedy, this is a failure on the part of the comedian. However, in algorithm design, this is a failure on the part of the problem solver (audience).

#### **Another Difficult Problem**

Why is one side of the V in a flock of Geese usually longer than the other?



#### **Related Problems**

Why is one side of the V in a flock of Geese usually longer than the other?



#### Because there are more Geese in it!

This joke sets up a Canyon Trap that leads you to believe that the answer is profound; whereas it is instead simple.

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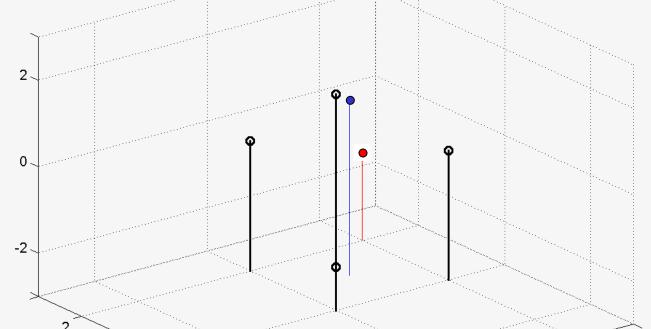
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## **The Problem of Source Separation**

Consider the problem of localizing two sound sources (red and blue) and describing their signals with a 500-point time-series.



This is a  $2^*3 + 2^*500 = 1006$  dimensional problem.

With a 1006 dimensional problem we must deal with:

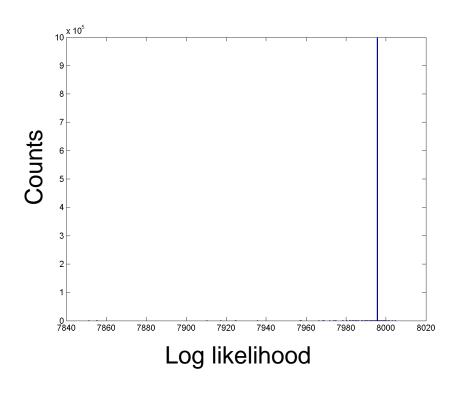
**Wilderness Trap**: Enormous volume to search. Even if the solution occupies 1/10 the volume along each parameter, the relative volume of the solution space is 10<sup>-1006</sup>!

**Oasis Traps**: We expect local solutions. These are expected to increase dramatically with dimension.

But this may be surprising...

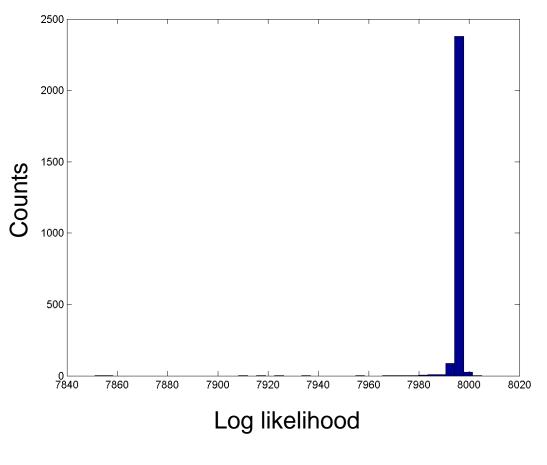
This is a histogram of the log likelihood of 1 MILLION samples uniformly drawn from the 1006 dimensional space.

The space is VERY flat!



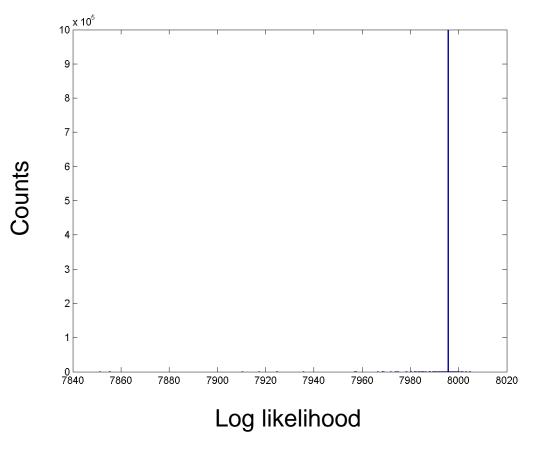
## The Space is EXTREMELY FLAT!

Out of 1 MILLION samples, only 2527 samples were greater than 7996.3 or less than 7995.3



## **Nowhere Near a Solution**

The peak Log Likelihood is at 17700, with ONE MILLION samples, we are still exp(10000) away from the solution!



# Why Source Separation is Difficult

**Wilderness Trap**: Enormous volume to search. Even if the solution occupies 1/10 the volume along each parameter, the relative volume of the solution space is  $10^{-1006}$ !

**Oasis Traps**: We expect local solutions. These are expected to increase dramatically with dimension.

**Clueless Plateau**: Extensive regions of the space are noninformative

**Small Solution Volume:** The solution occupies an extremely small volume in the entire solution space. Moreover, there are often gates, which are peaks on top of peaks.

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#### Heuristic Solutions constitute Educated Guesses

These solutions rely on a set of various ideas:

- General Observations about the problem that constrain possible parameter values
- Approximations that constrain possible parameter values
- Idealizations or Simplifications that focus on a sub-problem and thus solve the problem within a subspace of the original problem
- Marginalization over a subspace focused the inference on a sub-problem

Many of the clever solutions seen in the literature are relying on heuristics. These are often computationally fast, but used alone, **heuristics are not consistently successful** 

Examples in source separation

- Examine frequency bands unique to a source to pin down its contribution to the mixture
- In conversation, use fact that sources are not emitting at the same time to find temporal regions where the recordings are from a single source
- Decompose mixtures into a sparse library

# **Exploration via Sampling**

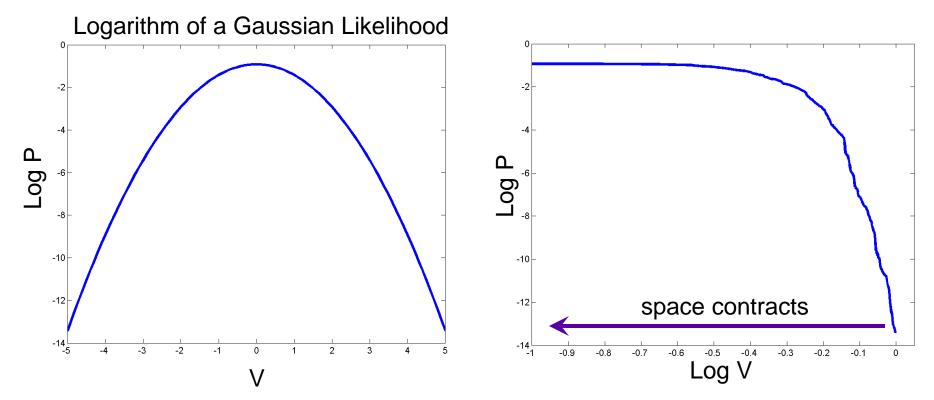
Sampling Techniques such as those collectively labeled Monte Carlo methods constitute Exploration.

- Metropolis-Hastings
- Gibbs Sampling
- Particle Filters
- Importance Sampling
- Nested Sampling (Skilling 2005)

The advantages are that they are robust. The disadvantages are that in difficult problems, they can be slow and may not converge to the right solution.

# Sorted Log Likelihoods reveal Structure

Skilling's Nested Sampling relies on sorting the log Likelihood values of samples drawn from the Prior Probability



This turns all problems into 1-D problems

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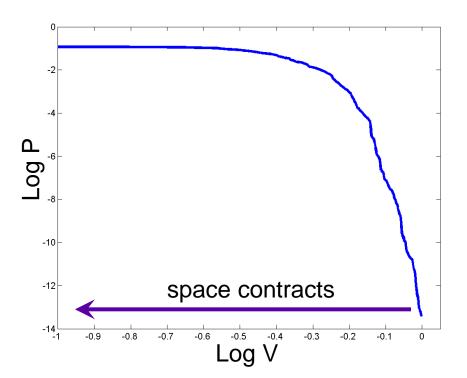
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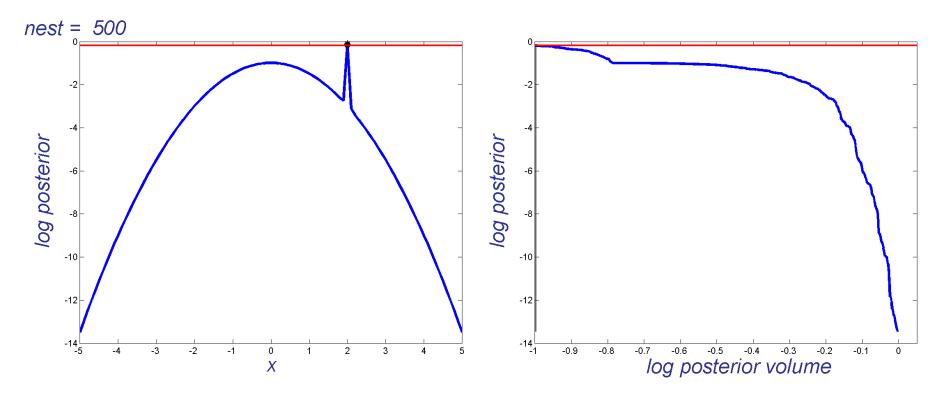
# **Typical Behavior**

In a well-behaved problem the log likelihood increases monotonically with a monotonically decreasing volume.

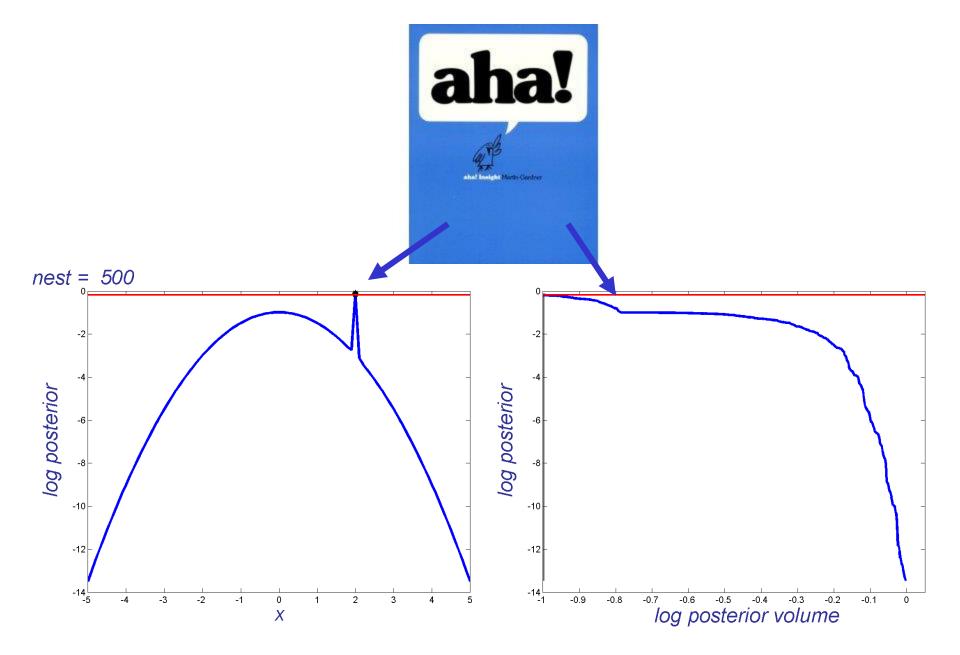
This can be viewed as a density of states.



# **Typical Behavior**



Problems with peaks on peaks are mildly difficult. In statistical mechanics, one interprets these inflections as phase transitions.



## Conclusions

#### Algorithm Design is Problem-Solving!

Effective problem-solving relies both on exploration and educated guesses.

Choosing samples randomly encourages exploration.

Including samples recommended by heuristics incorporates educated guesses.

Such a union is still fully-Bayesian!

## **Thank You for Your Kind Attention**

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